



# Sensitivity analysis of Al-based algorithms for autonomous driving on optical wavefront aberrations induced by the windshield

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### **Problem Scope**

- Autonomous driving heavily relies on Computer Vision
- Autobahn use case requires long-focus cameras
- Long-focus cameras are very sensitive for optical aberrations



- Aberrations blur the image by the PSF of the optical system
- Optical aberrations induced by the windshield generate dataset shifts
- Dataset shifts deteriorate the performance of AI-algorithms
- Safeguarding autonomous driving functionalities puts optical requirements on the windshield
- Bijectivity between optical system metric and AI merit function required
- Optical KPI needs to be measurable for quality assurance purposes
- How does this metric correlate to current governing quality standards?



![](_page_0_Figure_18.jpeg)

accuracy [%]

Average

![](_page_0_Picture_19.jpeg)

![](_page_0_Picture_20.jpeg)

![](_page_0_Picture_21.jpeg)

![](_page_0_Picture_22.jpeg)

![](_page_0_Picture_23.jpeg)

#### Al-algorithms vs. optical system performance

MTF at half Nyquist correlates poorly to the AI-KPIs:

![](_page_0_Figure_26.jpeg)

## **Results to:**

#### Prediction uncertainty vs. optical system performance

 $\alpha_{a}$ 

Zernike

decomposition

Model overconfidence increases: 

![](_page_0_Figure_30.jpeg)

![](_page_0_Figure_31.jpeg)

![](_page_0_Figure_32.jpeg)

Optical informative gain shows slightly stronger correlation:

![](_page_0_Figure_34.jpeg)

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independent optical aberrations has been quantified in terms of Shapley values, where the Zernike coefficients serve as features of the optical model:

**Results to:** 

- Refractive power as the wavefront aberration curvature along a specified direction – is fundamentally incapable of capturing information about the PSF and the oblique astigmatism  $(Z_3)$  in particular.
- The System MTF is not multiplicative due to the LTI-constraint violation.

![](_page_0_Picture_39.jpeg)

![](_page_0_Picture_40.jpeg)

![](_page_0_Picture_41.jpeg)